



Session 5: Lecture 7:

# **Agent-Based Urban Models**

Hybrid Modelling of Crowds

**Ateen Patel, CASA**

<http://www.casa.ucl.ac.uk>

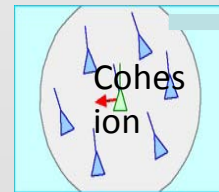
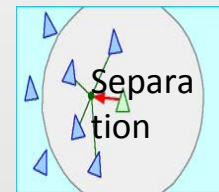
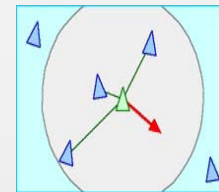
# Hybrid modelling of crowds

Ateen Patel, March 2013

Supervised by Mike Batty, Andy-Hudson Smith  
and Anthony Steed

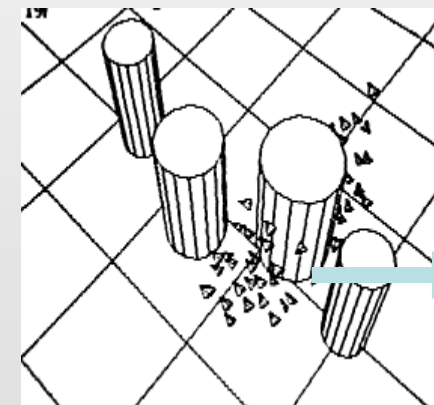
# A little bit of history

- Boids model – Craig Reynolds, 1987



Alignm  
ent

Breakdown of behaviours



Computer simulation

# Appearances of the boids model in various guises



Stanley and Stella in:  
Breaking the ice (1987)



The Lion King (1994)



Batman Returns (1992)

# Overview

- Motivation
- Applications
- Microscopic Model
- Macroscopic Model
- Hybrid Model
- Summary

# Motivation and Aim

- Real world crowds are ubiquitous
- Current models require trade-offs:
  - Complex behavior vs computation time
- Real-time applications: crowds are still rare, interactive worlds are mostly ghost towns (urban planning and games)

# Approaches and Applications

- Common approaches:

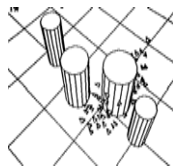
- Particle systems
- Agent based models
- Cellular automata
- Probability networks
- Social-force networks

- Applications

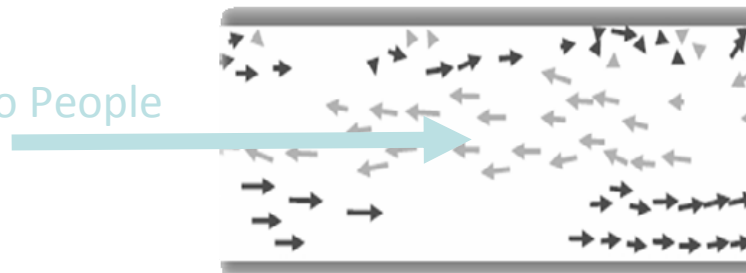
- Entertainment industry (animation production, computer games)
- Architecture (planning of buildings, towns, visualization)
- Safety science (evacuation of buildings)

# Microscopic Model

- Simulating dynamic features of escape panic i.e., Social Forces
  - Characteristics:
    - People move or try to move considerably faster than normal
    - Individuals start pushing, and interactions become physical
    - Moving becomes uncoordinated
    - At exits, arching and clogging are observed
    - Jams build up
    - Pressure on walls and steel barriers increase
    - Escape is further slowed by fallen or injured people acting as 'obstacles'



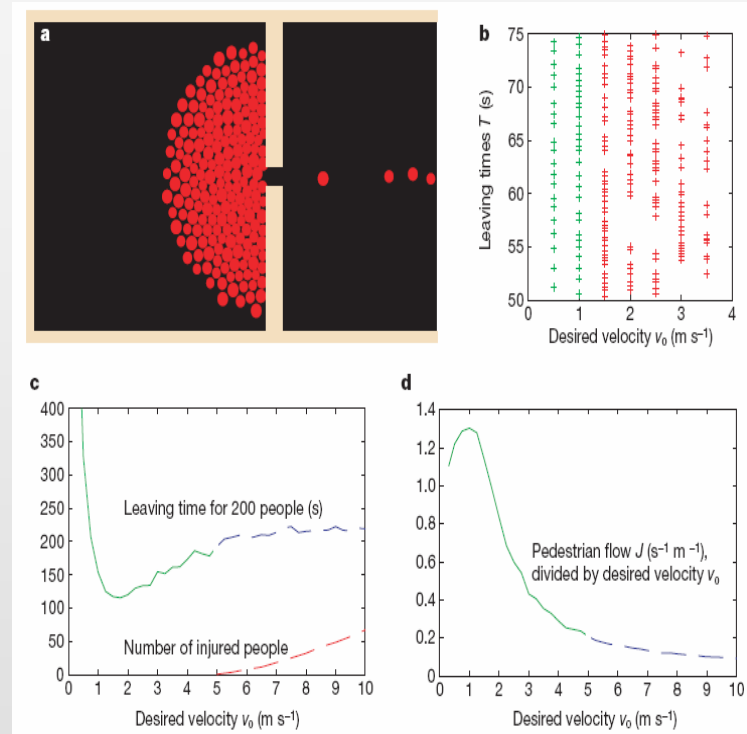
Boids to People





# Governing Equations

$$m_i \frac{d\mathbf{v}_i}{dt} = m_i \frac{v_i^0(t)\mathbf{e}_i^0(t) - \mathbf{v}_i(t)}{\tau_i} + \sum_{j(\neq i)} \mathbf{f}_{ij} + \sum_W \mathbf{f}_{iW}$$



Velocity  
change =

Mass  
x

desired speed x direction - actual  
velocity  
time

characteristic

Interaction  
Forces

# Advantages and Limitations

- Capability of modelling individual behaviour
- Models the property of emergence, where complex life-like global behaviour arises from the interaction of simple rules.
- As computation time increases per-agent, this limits the speed and scalability of the model.

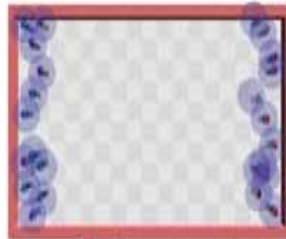
# Macroscopic Model

- Continuum Crowds
  - Characteristics
    - Continuum based model not agent based
    - Think of it as a continuous cellular automata
    - Goal oriented
    - Always trying to reach a goal – Goal oriented
    - Always trying to move at fastest speed
    - Always trying to move with least discomfort
    - Groups share similar preferences



Compute a set of grids representing state.

*Density Grid:* Indicates people's static locations.



*Goal Grids:* Indicate people's desired locations.



*Boundary Grids:* Indicate impassible grid cells.



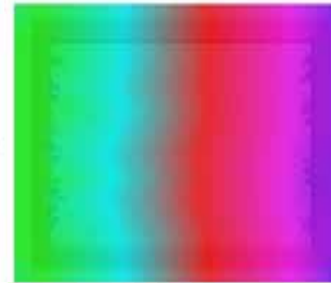
*Other grids...*

⋮

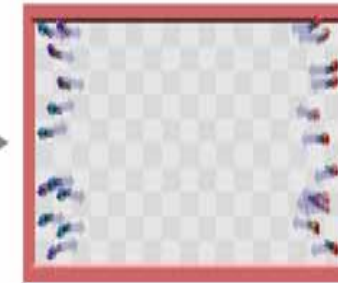
- Convert crowd into a density grid
- For each group:
  - Construct Unit Cost Field
    - Compute Speed field
    - Calculate Cost field based on groups sharing similar preferences
  - Construct final potential field based on the cost field
- Construct a velocity field – think of it as a continuous cellular automata
- Update agent's positions based on velocity at the cell

Based on density, topographical and flow speed

Combine grids into a set of potential fields.



Use potential fields to update people's positions.



$$\dot{\mathbf{x}} = -f_T(\mathbf{x}, \theta) + \left( \frac{\rho(\mathbf{x} + r\mathbf{n}_\theta) - \rho_{min}}{\rho_{max} - \rho_{min}} \right) \cdot$$

$$\left( \bar{\mathbf{v}}(\mathbf{x} + r\mathbf{n}_\theta) \cdot \mathbf{n}_\theta - f_{max} + \left( \frac{\nabla h(\mathbf{x}) \cdot \mathbf{n}_\theta - s_{min}}{s_{max} - s_{min}} \right) (f_{min} - f_{max}) \right) \cdot$$

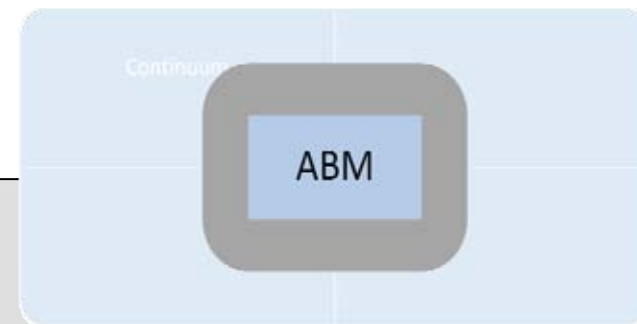
$$\frac{\nabla \phi(\mathbf{x})}{\left( \frac{\alpha f + \beta + \gamma g}{f} \right)}$$

# Advantages and Limitations

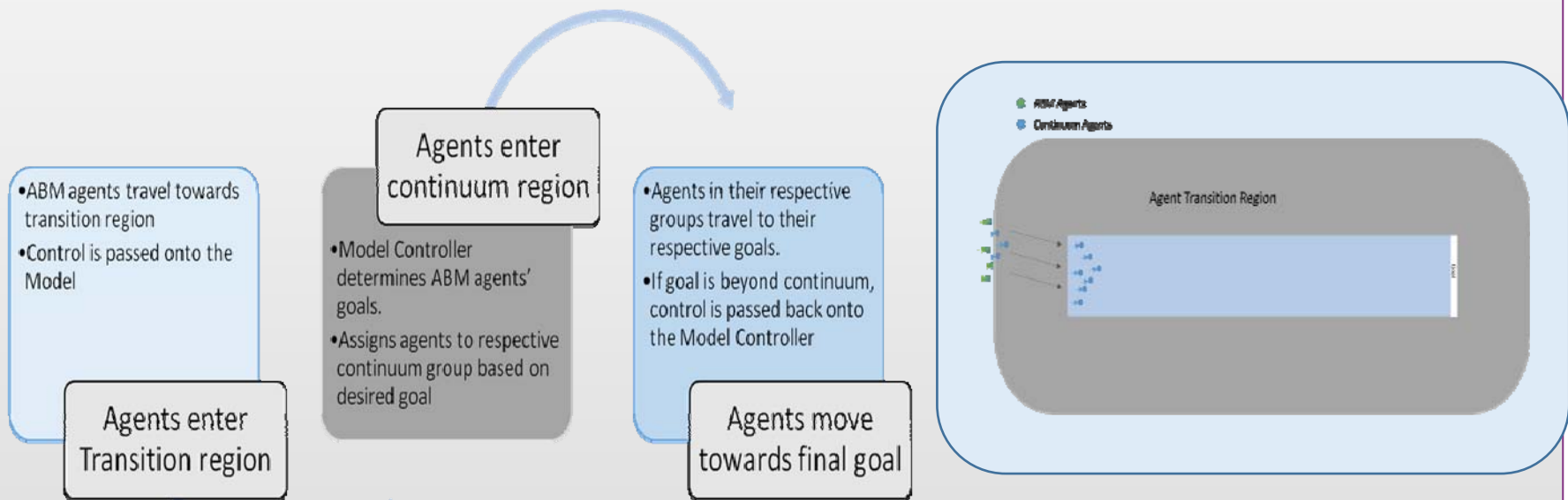
- The computation time per agent decreases dramatically vs agent based models, as the fluid once computed acts on the group as a whole. Agents do not make individual decisions, but are directed by the fluid.
- Clearly, agents are far more individual in real crowds than this continuum model likes us to believe. What can we do about adding individualism to this model?

# Hybrid Model

- Characteristics
  - Model divided into exclusive regions that are interdependent
  - The region of interest is modeled as the ABM
  - The remainder of the area is modeled as the faster continuum model
  - Creates flexibility and scalability for large-scale flows with complex dynamics



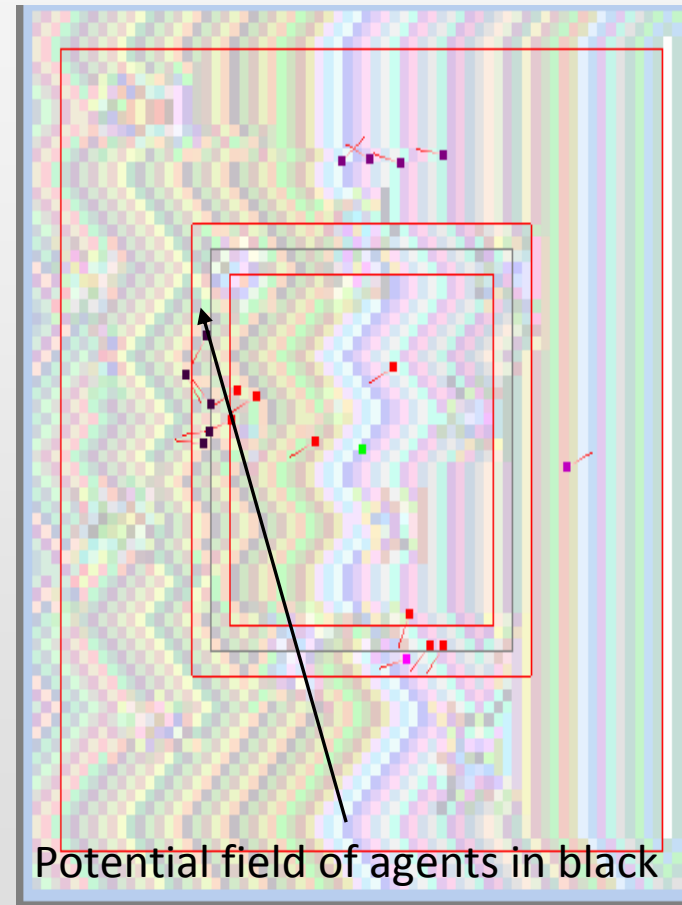
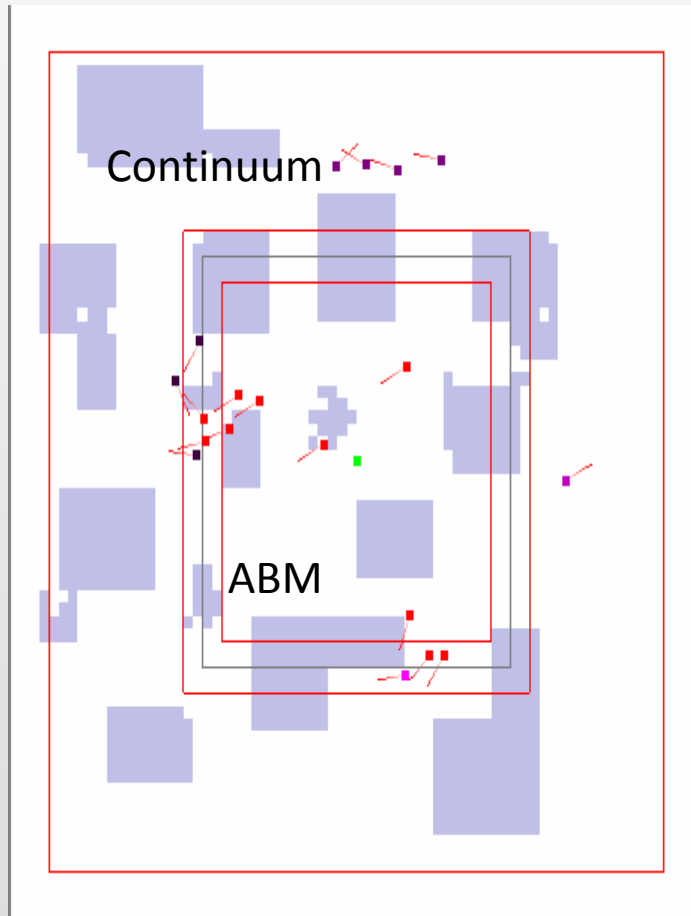
# Transition: ABM -> Continuum



## Model Controller

# A couple screen shots

goal



Agents in black try to move from left to right



# What the final scenario creation can lead to

